

Algorithmic Game Theory

Auction Games and Games with Dynamic population

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Recall: Smoothness for auctions

Auction game is (λ, μ) -smooth if for some $\mu > 1, \lambda > 0$ and some strategy s^* and all s we have

$$\sum_i u_i(s_i^*, s_{-i}) \geq \lambda \text{opt} - \mu R(s)$$

$R(s)$ = revenue at bid vector s (usually $\mu=1$)

Theorem: [Syrgkanis-T'13] Price of anarchy for any (λ, μ) -auction game is at most μ/λ for full information games.

- If s_i^* depends all of (v_1, \dots, v_n) then applied also to as well as Bayesian game with independent priors.
- If s_i^* depends only on v_i then applied also with dependent priors.

Social welfare: $\sum_i u_i(s) + R(s)$

Topic 1: Auction for many items

Two cases:

1. Additive value $v_i(A_i) = \sum_{j \in A_i} v_{ij}$
Separate analysis for each buyer
2. Unit demand: $v_i(A_i) = \max_{j \in A_i} v_{ij}$ (free disposal)
First price item action each: yesterday $(1/2, 1)$ -smooth

Extension theorem: smooth auctions when combined remain smooth
Individual item auctions...Christodoulou, Kovacs, Schapire ICALP'08

Truthful auction: VCG

Analog of second price:

- Compute $\max \sum_j v_j(A_j^*)$ over all valid allocation (A_1^*, \dots, A_n^*)
- Charge player i the externality he poses to others:

$$p_i = \max \sum_{j \neq i} v_j(A_j) - \sum_{j \neq i} v_j(A_j^*)$$

Optimizes social welfare and is truthful

Centralized, and computation?

Valuations:

- Complements are a problem:



- Two bidders, with item set S of n items, $k \ll n$
 - Bidders 1..k: $v_1(A) = \max_{j \in A} v_{1j}$ and $v_{1j}=1$ all j
 - Bidder $k+1$: $v_2(S) = n - k$ all other sets 0

No complements

Theorem. Valuation Hierarchy

Gross Substitutes \subseteq Decreasing marginal utility \subseteq XOS \equiv Fractionally Subadditive

Extending Lehmann et al'01 and Feige'06

XOS valuation: For any allocation $x_i = (x_i^1, \dots, x_i^m)$

$$v_i(x_i) = \max_{k \in K} \sum_{j \in [m]} v_{ij}^k(x_i^j)$$

for some set of additively separable valuations K .

Example:

unit demand $v_i(x_i^1, \dots, x_i^m) = \max_j v_i(x_i^j)$

No complements (cont)

- Decreasing marginal utility = Submodular:
 $v(A + j) - v(A) \geq v(B + j) - v(B)$ whenever $A \subset B$

Theorem. Submodular valuation can we written as XOS

Proof: For each ordering of the elements σ let v^σ be the marginal value in ordering σ

$$v_j^\sigma = v(S_j^\sigma) - v(S_{-j}^\sigma) :$$

where S_j^σ is prefix till item j, and S_{-j}^σ prefix without j.

Note: max involves exponentially many

Simultaneous Composition

Theorem (Syrgkanis-T'13): simultaneous item auctions where each is (λ, μ) -smooth and players have fractionally subadditive valuations, then composition is also (λ, μ) -smooth.

Note: with many items, learning is hard!

Simultaneous Composition

Theorem (Syrgkanis-T'13): simultaneous item auctions where each is (λ, μ) -smooth and players have fractionally subadditive valuations, then composition is also (λ, μ) -smooth.

Proof: valuation $v(S)$ is fractionally subadditive \Rightarrow maximum of linear functions: $v(S) = \max_k \sum_{(x \in S)} v_j^k$

- optimal allocation S_1^*, S_2^*, \dots values $v_i(S_i^*) = \sum_{(j \in S_i^*)} v_j^{[k_i^*]}$
- Each auction smooth, so user i bids (not regrets) in auction j for value $v_j^{[k_i^*]}$
- Real value $v_i(A) \geq \sum_{(j \in A)} v_j^{[k_i^*]}$

Additional Topic: Dynamic Population

Main stability assumption in the literature:
 • Game is repeated identically and nothing changes

Dynamic population model:

At each step t each player i
 is replaced with an arbitrary new player with probability p

In a population of N players, each step, Np players replaced in expectation

Learning players can adapt....

Goal:

Bound average welfare assuming **adaptive** no-regret learners

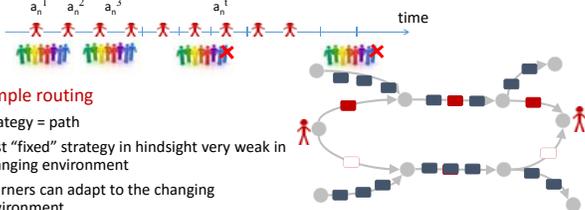
$$PoA = \lim_{T \rightarrow \infty} \frac{\sum_{t=1}^T Cost(s^t; v^t)}{\sum_{t=1}^T Opt(v^t)}$$

where v^t is the vector of player types at time t

even when the rate of change is high, i.e. a large fraction can turn over at every step.

Need for adaptive learning

a_1^1	a_1^2	a_1^3	a_1^t
a_2^1	a_2^2	a_2^3	a_2^t
\dots	\dots	\dots	\dots
a_n^1	a_n^2	a_n^3	a_n^t



Example routing

- Strategy = path
- Best "fixed" strategy in hindsight very weak in changing environment
- Learners can adapt to the changing environment

Need for adaptive learning

Example 2: matching (unit demand)

- Strategy = choose a mode
- Best "fixed" strategy in hindsight very weak in changing environment
- Learners can adapt to the changing environment

Adaptive Learning

• Adaptive regret [Hazan-Seshadiri, Luo-Schapire]
for all player i , strategy x and interval $[\tau_1, \tau_2]$

$$R_i(x, \tau_1, \tau_2) = \sum_{t=\tau_1}^{\tau_2} cost_i(s^t; v^t) - cost_i(x, s_{-i}^t; v^t) \leq o(\tau_2 - \tau_1)$$

rates of $\sim \sqrt{\tau_2 - \tau_1}$

⇒ Regret with respect to a strategy that changes k times $\leq \sim \sqrt{kT}$

Result (Lykouris, Syrgkanis, T'16) :

Bound average welfare close to Price of Anarchy for Nash
even when the rate of change is high, $p \approx \frac{1}{\log n}$ with n players
assuming **adaptive** no-regret learners

- Worst case change of player type ⇒ need for adapting to changing environment
- Sudden large change is unlikely

No-regret and Price of Anarchy

Low regret:

$$R_i(x) = \sum_{t=1}^T cost_i(a^t; v^t) - cost_i(x, a_{-i}^t; v^t) \leq o(T)$$

Best action varies with choices of others...
Consider Optimal Solution
Let $x = s_i^*$ be the choice in OPT

No regret for all players i :
 $\sum_i cost_i(a^t) \leq \sum_i cost_i(s_i^*, a_{-i}^t)$
Players don't have to know s_i^*

Adapting smoothness to dynamic populations

Inequality we "wish to have"

$$\sum_t cost_i(s^t; v^t) \leq \sum_t cost_i(s_i^{*t}, s_{-i}^t; v^t)$$

where s_i^{*t} is the optimum strategy for the players at time t .

with stable population = no regret for s_i^{*t}
Too much to hope for in dynamic case:

- sequence s^{*t} of optimal solutions changes too much.
- No hope of learners not to regret this!

Change in Optimum Solution

True optimum is too sensitive

- Example using matching
- The optimum solution
- One person leaving
- Can change the solution for everyone

• Np changes each step → No time to learn!! (we have $p \gg 1/N$)

Theorem (high level)

If a game satisfies a "smoothness property" [Roughgarden'09]
 The welfare optimization problem admits an approximation algorithm whose outcome \tilde{s}^t is stable to changes in one player's type

Then any adaptive learning outcome is approximately efficient even when the rate of change is high.

Proof idea: use this approximate solution as \tilde{s}^t in Price of Anarchy proof
 With \tilde{s}^t not changing much, learners have time to learn not to regret following \tilde{s}^t
 Note: learner doesn't have to know \tilde{s}^t !!

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Do Stable Solutions Exist?

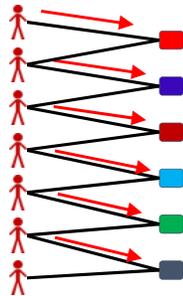
- How close can we remain to the optimum, while being stable?
- How much change can we manage, while being stable?

Recall: Regret of adaptive learning is bounded by $\leq \sqrt{kT}$
 with respect to any strategy that changes k times

Stable \approx Optimum in Matching

True optimum is too sensitive

- Use greedy allocation: assign large values first (loss of factor of 2)
- Use coarse approximation of value, e.g., power of 2 only
- Potential function argument: increase in log value of allocation only $m \log v_{max}$, decrease due to departures



Use Differential Privacy \rightarrow Stable Solutions

Joint privacy [Kearns et al. '14, Dwork et al. '06]

A randomized algorithm is jointly differentially private if

- when input from player i changes
- the probability of change in solution of players other than i is smaller than ϵ

- Turn a sequence of randomized solutions to a randomized sequence with small number of changes using Coupling Lemma
- and handling "failure probabilities" of private algorithms

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Application 1: Large Congestion Games

- Using joint differentially private algorithm of Rogers et al EC'15,
 - the (5/3, 1/3)-smoothness congestion with affine cost:
- Theorem.** Atomic congestion game with m edges, and affine and increasing costs:

$$\frac{1}{T} \sum_t Cost(s^t; v^t) \leq 2.5(1 + \epsilon) \frac{1}{T} \sum_t OPT(v^t)$$

with $p = O\left(\frac{poly(\epsilon)}{poly(m) polylog(n)}\right)$ if each player controls only a $1/n$ fraction of the total flow.

Almost a constant fraction of change each step: dependence on number of players only polylog

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Other Applications

Using joint differentially private algorithm of Hsu et al '14

Theorem 2. Matching markets if values are $[\rho, 1]$

$$\frac{1}{T} \sum_t W(s^t; v^t) \geq \frac{1}{4(1+\epsilon)} \frac{1}{T} \sum_t OPT(v^t) \text{ with } p = O\left(\frac{\rho^2 \epsilon^2}{polylog(m, 1/\rho, 1/\epsilon)}\right)$$

Theorem 3. Large Combinatorial Markets with Gross-Substitutes

$$\frac{1}{T} \sum_t W(s^t; v^t) \geq \frac{1}{2(1+\epsilon)} \frac{1}{T} \sum_t OPT(v^t) \text{ with } p = O\left(\frac{\rho^5 \epsilon^5}{m polylog(n)}\right)$$

Each item in large supply $\Omega\left(polylog(n) \log\left(\frac{1}{\epsilon}, \frac{1}{\rho}\right)\right)$ and $\theta(n)$ items

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Conclusions/summary

- Analyzed quality of outcomes in games
 - Congestion games
 - Auction games
- General technique: smoothness (Roughgarden'09, Syrgkanis-T'13)
 - Extension theorem to Bayesian games
 - Extension theorem to valuations to multiple items and valuations without complements
- Focus on learning outcomes in games:
 - Good way to adapt to opponents
 - No need for common prior
 - Takes advantage of opponent playing badly.
 - Learning players do well even in dynamic environments

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