

Summer School Valparaiso

Wasserstein and MMD penalizations for
Unbalanced Optimal Transport

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Objective of the talk

- Recall of Unbalanced Optimal Transport
- Shortcomings of UOT
- Contribution: A new penalization on the marginals

Disclaimer

- Work in progress
- Not technical talk

Unbalanced Optimal Transport

OT: Recall

The Wasserstein distance: optimal displacement of mass

$$\text{OT}(\mu_1, \mu_2) = \inf_{\pi \in \Pi(\mu_1, \mu_2)} \int_{\mathbb{R}^d \times \mathbb{R}^d} \|x - y\|_2^2 d\pi(x, y) \quad (1)$$

$\Pi(\mu_1, \mu_2) \stackrel{\text{def}}{=} \{ \pi \in \mathcal{M}_+(\mathbb{R}^d \times \mathbb{R}^d) \text{ s.t. } \pi(\mathbb{R}^d \times A) = \mu_2(A) \text{ and } \pi(A \times \mathbb{R}^d) = \mu_1(A), \\ \forall A \subset \mathbb{R}^d \}$

- Hard (mass-preserving) hard constraint on the marginal $\Rightarrow |\mu_1| = |\mu_2|$
- When $\mu_1 = \sum_{i=1}^n a_i \delta_{x_i}$ and $\mu_2 = \sum_{j=1}^m b_j \delta_{y_j}$:

$$\text{OT}(\mu_1, \mu_2) = \min_{P \in U(a, b)} \langle C, P \rangle \quad (2)$$

with $C_{ij} = \|x_i - y_j\|_2^2$ and $U(a, b) \stackrel{\text{def}}{=} \{ P \in \mathbb{R}_+^{n \times m} \text{ s.t. } P 1_m = a \text{ and } P^\top 1_n = b \}$

UOT: Definition

Relax the hard marginal constraint of OT by soft constraint [CPSV15]

$$\begin{aligned} \text{UOT}(\mu_1, \mu_2) = \inf_{\pi \in \mathcal{M}_+(\mathbb{R}^d \times \mathbb{R}^d)} & \int_{\mathbb{R}^d \times \mathbb{R}^d} \|x - y\|_2^2 d\pi(x, y) \\ & + \lambda_1 \text{KL}(\pi^1, \mu_1) + \lambda_2 \text{KL}(\pi^2, \mu_2) \end{aligned} \quad (3)$$

$$\pi^1 = \pi(\cdot \times \mathbb{R}^d), \pi^2 = \pi(\mathbb{R}^d \times \cdot), \lambda_1, \lambda_2 > 0$$

- Not necessarily $|\mu_1| = |\mu_2|$
- Generally: KL or TV or ℓ_2 penalization
- π^i same support μ_i
- When $|\mu_1| = |\mu_2|$, $\text{UOT} \xrightarrow{\lambda \rightarrow \infty} \text{OT}$

UOT: Definition

Can be rewritten as

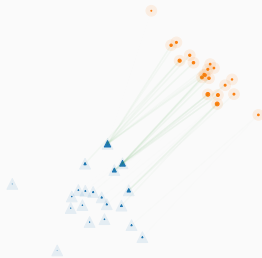
$$\begin{aligned} \text{UOT}(\mu_1, \mu_2) = & \inf_{\pi \in \mathcal{M}_+(\mathbb{R}^d \times \mathbb{R}^d)} \text{OT}(\pi^1, \pi^2) \\ & + \lambda (\text{KL}(\pi^1, \mu_1) + \text{KL}(\pi^2, \mu_2)) \end{aligned} \quad (4)$$



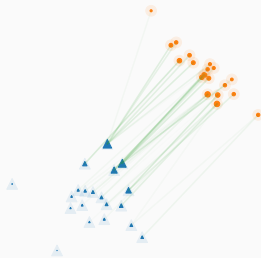
- π^1, π^2 proxies for μ_1, μ_2
- Atoms weights (but not locations) can change from π^i to μ_i
- Masses of $|\mu_j|$ can be informative

UOT: First Example

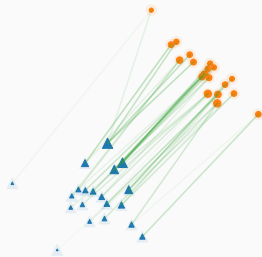
$\lambda = 5$



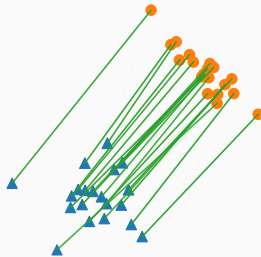
$\lambda = 8$



$\lambda = 15$



$\lambda = 500$



μ_1

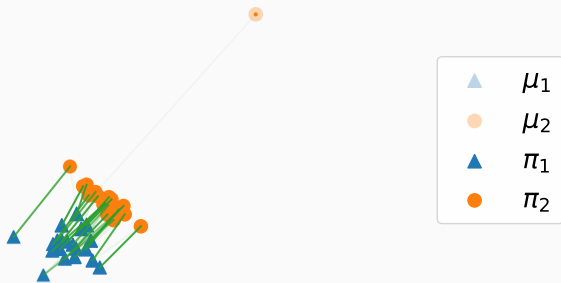
μ_2

π_1

π_2

UOT: Outliers

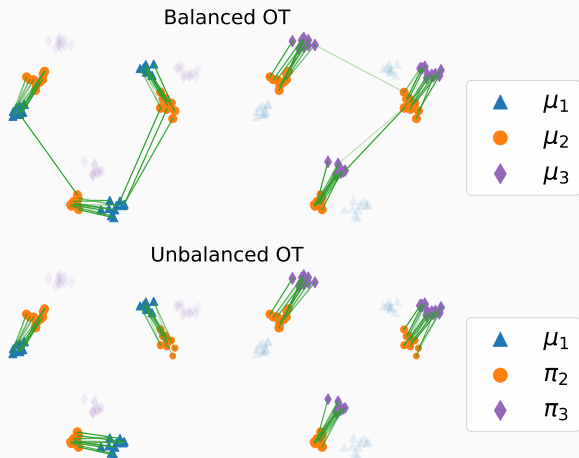
Interesting case: μ_2 is *infected* by outliers



- UOT seems to be robust to outliers

UOT: Birth and Death

Find a trajectory when the size of clusters can vary



- Can deal with birth and death of population [SST⁺19]

Drawbacks of UOT

Current penalizations compare π^i with μ_i vertically

$$\text{KL}(\pi^1, \mu_1) = \sum_{i=0}^n a'_i \log\left(\frac{a'_i}{a_i}\right) - a'_i + a_i, \quad (5)$$

$$\mu_1 = \sum a_i \delta_{x_i} \text{ and } \pi^1 = \sum a'_i \delta_{x_i}$$

- No geometric information of support
- Change of weights driven by $\|x_i - y_j\|_2^2$
- π^i can be misleading as proxy of μ_i

Some Toy Example - Outliers

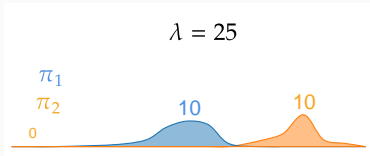
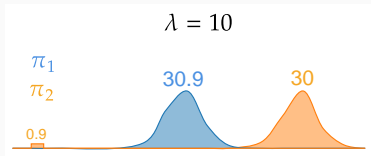
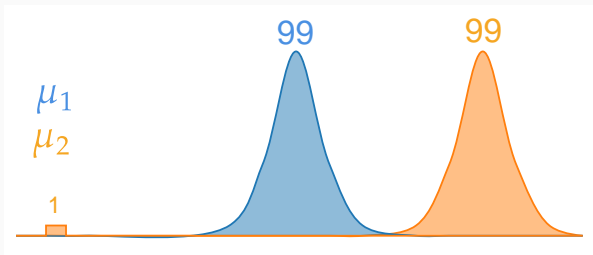


Figure: Source distribution μ_j (up) and proxies π_j for KL penalization (bot)

Some Toy Example - Birth and Death

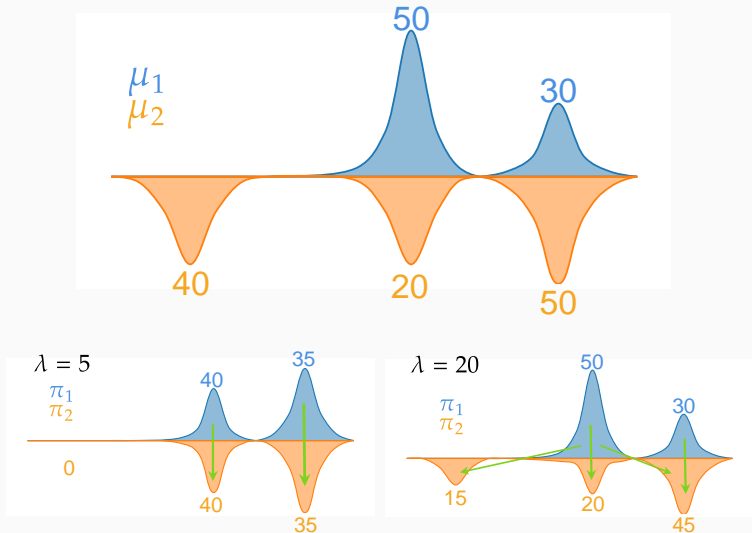


Figure: Source distribution μ_i (up) and proxies π_i for KL penalization (bot)

A New Penalization

Geometric Penalization

Penalization should consider the geometry of the marginals' support

- $\text{OT}(\pi^i, \mu_i)$
- $\text{MMD}(\pi^i, \mu_i)$

where

$$\begin{aligned} \text{MMD}(\mu_1, \pi^1) &= \int_{\mathbb{R}^d \times \mathbb{R}^d} k(x, x') d\mu_1(x) d\mu_1(x') \\ &\quad + \int_{\mathbb{R}^d \times \mathbb{R}^d} k(x, x') d\pi^1(x) d\pi^1(x') \\ &\quad - 2 \int_{\mathbb{R}^d \times \mathbb{R}^d} k(x, x') d\mu_1(x) d\pi^1(x) \quad (6) \end{aligned}$$

- Here Gaussian kernel $k(x, x') = \exp\left(\frac{-\|x-y\|_2^2}{2\sigma^2}\right)$, $\sigma > 0$

Geometric Penalization - OT

$$\begin{aligned} \text{UOT}(\mu_1, \mu_2) = & \inf_{\pi \in \mathcal{M}_+(\mathbb{R}^d \times \mathbb{R}^d)} \int_{\mathbb{R}^d \times \mathbb{R}^d} \|x - y\|_2^2 d\pi(x, y) \\ & + \lambda_1 \text{OT}(\pi^1, \mu_1) + \lambda_2 \text{OT}(\pi^2, \mu_2) \end{aligned} \quad (7)$$

- $|\pi^j| = |\mu_j| \Rightarrow |\mu_1| = |\mu_2|$
- Conserve overall mass: not death/birth but rather *redistribution of mass*
- Avoid cluster collapse

Geometric Penalization - MMD

$$\begin{aligned} \text{UOT}(\mu_1, \mu_2) = & \inf_{\pi \in \mathcal{M}_+(\mathbb{R}^d \times \mathbb{R}^d)} \int_{\mathbb{R}^d \times \mathbb{R}^d} \|x - y\|_2^2 d\pi(x, y) \\ & + \lambda_1 \text{MMD}(\pi^1, \mu_1) + \lambda_2 \text{MMD}(\pi^2, \mu_2) \quad (8) \end{aligned}$$

- Not necessarily $|\mu_1| = |\mu_2|$
- Lot of close atoms \Rightarrow expensive to discard
- Few close atom \Rightarrow easy to discard

Toy Examples

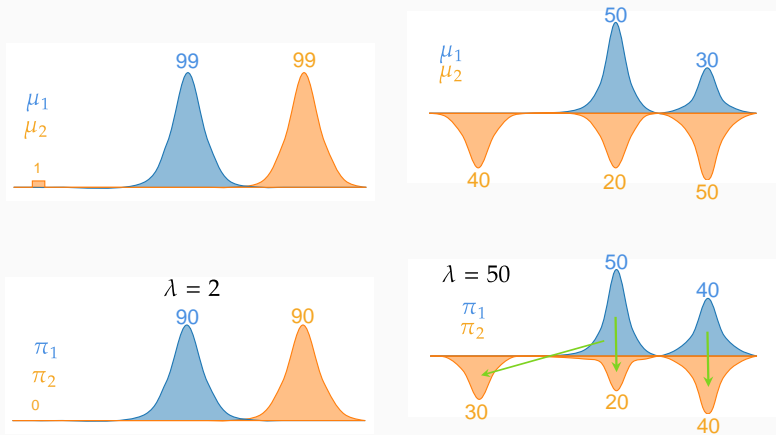


Figure: Source distribution μ_i (up) and proxies π_i for MMD penalization (bot) for Outliers (left) and Birth death (right)

Optimization

- UOT_D is a convex minimization problem
- Sinkhorn iterates [CPSV18]:

$$u^{2l} = \text{prox}_{\lambda_1 D}^{\epsilon \text{KL}}(Gv^{2l-1}) \oslash Gv^{2l-1}, \quad v^{2l+1} = \text{prox}_{\lambda_2 D}^{\epsilon \text{KL}}(G^t u^{2l}) \oslash G^t u^{2l}$$

where $G = e^{-\|x-y\|_2^2/\epsilon}$ Gibbs Kernel and:

$$\text{prox}_{\lambda D}^{\epsilon \text{KL}}(z) = \text{argmin}_{u \in \mathbb{R}^n} \epsilon \text{KL}(u|z) + \lambda D(u|a), \quad \forall z \in \mathbb{R}^n$$

- OT and MMD more expensive than KL

Conclusion

Take home message:

- Proxies π^i must not be too far from μ_i
- Geometries of μ_i can be important
- MMD and OT penalization can be computed via Sinkhorn

Future works:

- Consider other penalizations:

$$\text{NLL}(\pi^i, \mu_i) \stackrel{\text{def}}{=} \int -\log \left(\int e^{-\frac{\|x-y\|^2}{2\sigma^2}} d\pi^i(x) \right) d\mu_i(y) \quad (9)$$

- Relax the fixed support constraint



Lenaic Chizat, Gabriel Peyré, Bernhard Schmitzer, and François-Xavier Vialard.

Unbalanced optimal transport: geometry and Kantorovich formulation.

2015.



Lenaic Chizat, Gabriel Peyré, Bernhard Schmitzer, and François-Xavier Vialard.

Scaling algorithms for unbalanced optimal transport problems.

Mathematics of Computation, 87(314):2563–2609, 2018.



Geoffrey Schiebinger, Jian Shu, Marcin Tabaka, Brian Cleary, Vidya Subramanian, Aryeh Solomon, Joshua Gould, Siyan Liu, Stacie Lin, Peter Berube, et al.

Optimal-transport analysis of single-cell gene expression identifies developmental trajectories in reprogramming.

Cell, 176(4):928–943, 2019.